# Comparison of single EWMA-type control charts based on Economicstatistical design

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## Keywords

EWMA charts; Simulation; Economic-statistical design; Cost model; Loss function

#### Abstract

A single exponentially weighted moving average (EWMA) chart is effectively used for monitoring the process mean and variance simultaneously. In this paper, three single EWMA-type control charts including sum of square EWMA (SS-EWMA), maximum EWMA (MaxEWMA), and EWMA-semicircle (EWMA-SC) charts are compared under Lorenzen and Vance's cost model integrating Taguchi's loss function. The optimal decision variables, namely sample size  $\mathbb{N}$ , sampling interval time h, control limit width L, and smoothing constant  $\lambda$ , are obtained by minimizing the expected cost function. Via simulations, the EWMA-SC charts have the smallest expected cost among these charts when a process has large shifts. However, the MaxEWMA charts have the smallest expected cost among these charts when a process mean shifts.

## 1. Introduction

The exponentially weighted moving average (EWMA) chart was first introduced by Roberts (1959) and has been widely used to improve the quality of a process when small process shifts are of interest. Various types of EWMA charts have been sequentially proposed to monitor process shifts. The variable sampling interval (VSI) EWMA chart (Saccucci et al., 1992) and the variable sample sizes and sampling intervals (VSSI) EWMA chart (Reynolds and Arnold, 2001) are efficient in improving detection ability than fixed-type EWMA charts. Auto correlated observations are always generated by continuous product manufacturing processes. Facing this scenario, it is not advisable to use traditional control chart for monitoring process shifts. Harris & Ross (1991) discussed the impact of autocorrelation on the performance of EWMA charts, and showed that the average run lengths of these charts were sensitive to the presence of autocorrelation. Most of control charts are established on the belief that the observations of a process are assumed to follow a normal distribution. When the observations are from a nonnormal or unknown distribution, it is suitable to construct control charts based on a nonparametric approach. Bakir (2006) proposed the nonparametric EWMA control charts for monitoring an unspecified in-control target process center. The proposed charts are more efficient than traditional normal-based control charts.

Two EWMA charts are usually required to jointly monitor small process mean and variance shifts. However, recently, significant attempts have been made to design a single EWMA chart for monitoring the process mean and variance simultaneously. Researchers have presented designs of various single EWMA control charts, such as the MaxMin EWMA chart (Amin et al., 1999), the Max chart (Chen and Cheng, 1998), the sum of squares EWMA (SS-EWMA) chart (Xie, 1999), the maximum EWMA (MaxEWMA) chart (Chen et al., 2001), the EWMA-semicircle (EWMA-SC) chart (Chen et al., 2004). These charts transform the sample mean and sample variance into a single plotting statistic or two plotting statistics, one representing the mean and the other representing the variance, on the same chart.

<sup>3&</sup>lt;sup>rd</sup> International Academic Conference in Paris (IACP), 10-11<sup>th</sup> August 2015, Paris, France

The aforementioned control charts are designed from a statistical perspective. Statistically designed control charts are often measured using the desired in-control average run length  $(ARL_0)$  and out-of-control average run length  $(ARL_1)$ . In addition to the statistical design of control charts, another design perspective involves economic design. The objective of an economic design control chart is to minimize the expected hourly loss cost. Duncan (1956) first proposed the economic model of a  $\overline{X}$  control chart, wherein three parameters, namely sample size n, sampling interval h, and control limit width L must be determined by cost minimization. This approach was generalized by Lorenzen and Vance (1986), who considered whether production continues during the period of searching for and/or repairing the assignable cause. Since then, various economic designs have been proposed for control charts (Montgomery, 1980; Ho and Case, 1994a; Park et al., 2004; Chou et al., 2006). Recently, Serel and Moskowitz (2008) and Serel (2009) presented a cost-minimization model to design the EWMA control chart based on quality-related production costs using the loss function.

However, Woodall (1986) found that the optimal economic design control chart has poor statistical performance. One significant problem is that the optimal economic solution usually yields a considerably large risk of Type I error. The in-control  $ARL_0$  of the control chart is usually too short to be practically acceptable. To improve the low statistical performance of the economic design control chart, some authors have expanded the pure economic model by incorporating additional statistical constraints, such as Saniga (1989), Montgomery et al. (1995), Chou et al. (2000) and Chen and Pao (2011), Yeong et al. (2013). Taguchi's quadratic loss function has been integrated into the economic-statistical design most recently by Huang and Lu (2015) and Lu et al. (2013), who respectively proposed the economic-statistical design of MaxEWMA and SSEWMA. They found that the economic-statistical design results in a large improvement in statistical performance and a small increase in cost.

The aim of this paper is to develop an economic-statistical design of the MaxDEWMA control chart by integrating the loss function into Lorenzen and Vance's cost model. A numerical simulation is conducted to minimize the cost function under *ARL* constraints. Moreover, a sensitivity analysis is conducted to assess the effects of the main input parameters on the objective function and decision variables. The rest of this paper is organized as follows. Section 2 reviews the literature on SS-EWMA, MaxEWMA and EWMA-SC charts. In Section 3, Lorenzen and Vance's cost model is briefly introduced. An illustrative example is presented in Section 4. Finally, Section 5 concludes.

#### 2. Review of the SS-EWMA, MaxEWMA and EWMA-SC charts

Suppose  $X_{ij}$ ,  $i = 1, 2, ..., and j = 1, 2, ..., n_i$  be observations of size,  $n_i$ , in the  $i^{th}$  sample having a normal distribution with mean  $\mu_0 + \delta \sigma_0$  and standard deviation  $\rho \sigma_0$ , where  $\mu_0$  and  $\sigma_0$  are defined as target values of the process. When  $\delta = 0$  and  $\rho = 1$  indicate that the process is in control, otherwise the process has changed or drifted.

Let  $\bar{x}_i$  and  $s_i^2$  denote the sample mean and sample variance of sample i, respectively. Then  $\bar{x}_i$ , i = 1, 2, ... are independent normal random variables with mean  $\mu_0 + \delta \sigma_0$  and variance

 $\rho^2 \sigma_0^2 / n_i$ ;  $(n_i - 1)S_i^2 / \rho^2 \sigma_0^2$  and i = 1, 2, ... are independent chi-square random variables with  $n_i - 1$  degrees of freedom; and  $\bar{X}_i$  and  $S_i^2$  are independent.

#### 2.1 The SS-EWMA control chart

According to Xie (1999), define the following two statistics:

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### August 2015

$$U_i = \frac{(\bar{X}_i - \mu_0)}{\sigma_0 / \sqrt{n_i}} \tag{1}$$

and

$$V_{i} = \Phi^{-1} \left\{ F\left[\frac{(n_{i} - 1)S_{i}^{2}}{\sigma_{0}^{2}}, n_{i} - 1\right] \right\},$$
(2)

where  $\Phi(z) = P(Z \le z)$ ,  $Z \sim N(0, 1)$ ,  $\Phi^{-1}$  is the inverse function of  $\Phi_{,}$  and  $F(w,v) = P(W \le w|v)$ , where  $W \sim \chi^{2}(v)$ . (These transformations and applications have been proposed by Quesenberry (1995))

Both  $U_i$  and  $V_i$  are independent standard normal random variables when the process in control, and that the distributions of  $U_i$  and  $V_i$  are both independent of the sample size  $n_i$ . Two EWMA statistics, each for the mean and variance, can be defined as

(3)

$$A_i = \lambda U_i + (1 - \lambda)A_{i-1} , \quad 0 < \lambda \le 1 , \quad i = 1, 2...,$$
 and

 $B_{i} = \lambda V_{i} + (1 - \lambda)B_{i-1} , \quad 0 < \lambda \le 1 , i = 1, 2...,$ (4) where  $A_{0}$  and  $B_{0}$  are the starting values, respectively. It is known that  $A_{i}$  and  $B_{i}$  are independent because  $U_{i}$  and  $V_{i}$  are independent, and when  $\delta = 0, \rho = 1$ , and  $A_{0} = B_{0} = 0$ , we have both  $A_{i} \sim N(0, \sigma_{A_{i}}^{2})$  and  $B_{i} \square N(0, \sigma_{B_{i}}^{2})$ , where  $\sigma_{A_{i}}^{2} = \sigma_{B_{i}}^{2} = \frac{\lambda}{2 - \lambda} \left[ 1 - (1 - \lambda)^{2i} \right]$ . We then define the statistic of the SS-EWMA chart by combing the above two EWMA statistics defined as  $SE_{i} = A_{i}^{2} + B_{i}^{2}$ , i = 1, 2, ...(5)

Because the statistic  $SE_i$  is non-negative, the SS-EWMA chart has only an upper control limit (UCL), which is given by

$$UCL = E(SE_i) + L\sqrt{Var(SE_i)}$$
(6)

where  $E(SE_i)$  and  $Var(SE_i)$  are the in-control mean and variance of the statistic  $SE_i$ , respectively. L is the control limit constant chosen to match the desired  $ARL_0$ . To achieve the desired  $ARL_0$ , the corresponding control limit constant L and the smoothing parameter  $\lambda$  is determined.

## 2.2 The MaxEWMA control chart

According to definition of Xie (1999), Chen et al. (2001) redefined the new MaxEWMA statistic defined as

$$M_i = \max\left\{ |A_i|, |B_i| \right\} \tag{7}$$

Because the statistic  $M_i$  is non-negative, the MaxEWMA chart has only an upper control limit (UCL), which is given by

$$UCL = E(M_i) + L\sqrt{Var(M_i)}$$
(8)

where  $E(M_i)$  and  $Var(M_i)$  are the in-control mean and variance of the statistic  $M_i$ , respectively. L is the control limit constant chosen to match the desired  $ARL_0$ . To achieve the desired  $ARL_0$ , the corresponding control limit constant L and the smoothing parameter  $\lambda$  is determined.

#### 2.3 The EWMA-SC control chart

According to Chen et al. (2004), the statistic of a SC chart is defined as:

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$$H_i = (\bar{X}_i - \mu)^2 + \frac{n_i - 1}{n_i} S_i^2, \quad i = 1, 2, \dots$$
(9)

Let  $H_i^* = \frac{n_i}{\sigma^2} H_i$ . The EWMA-SC statistic *SC<sub>i</sub>* can be defined from  $H_i^*$  as follows:

 $SC_i = \lambda H_i^* + (1 - \lambda)SC_{i-1}, \quad 0 < \lambda \le 1, \quad i = 1, 2, ...,$  (10) where  $\lambda$  is the smoothing constant while  $SC_0 = n$  is the starting value of  $SC_i$ . Because  $H_i^* \sim \chi^2(n)$  when  $\delta = 0, \rho = 1$  and  $n_1 = n_2 = \dots = n_i = n$ , and so we have the following results:  $E(SC) = E(H_i^*) = n_1$  (11)

$$E(SC_i) = E(H_i) = h, \qquad (11)$$

$$Var(SC_i) = \frac{\lambda \left[ 1 - (1 - \lambda)^{2i} \right]}{2 - \lambda} \cdot Var(H_i^*) = \frac{2n\lambda \left[ 1 - (1 - \lambda)^{2i} \right]}{2 - \lambda} \quad (12)$$

In addition, Equation (10) can be rewritten as:

$$SC_{i} = Y_{i} + Z_{i} + n,$$
(13)  
where  $Y_{i} = \lambda \left[ \frac{(\overline{X}_{i} - \mu)^{2}}{\sigma_{n}^{2} / n} - 1 \right] + (1 - \lambda)Y_{i-1} \text{ and } Z_{i} = \lambda \left[ (n-1)(\frac{S_{i}^{2}}{\sigma^{2}} - 1) \right] + (1 - \lambda)Z_{i-1} \text{ with } Y_{0} = Z_{0} = 0.$ 

Additionally, it is known that  $Y_i$  and  $Z_i$  are also independent because  $\overline{X}_i$  and  $S_i^2$  are independent.

The EWMA-SC chart only needs an upper control limit (UCL) as the  $SC_i$  is non-negative. The UCL corresponding to Equation (10) is given by:

$$UCL^{1} = E(SC_{i}) + L\sqrt{Var(SC_{i})} = n + L\sqrt{\frac{2n\lambda \left[1 - (1 - \lambda)^{2i}\right]}{2 - \lambda}}, \qquad (14)$$

and the UCL corresponding to Equation (13) is given by:

$$UCL^{2} = L\sqrt{\frac{2n\lambda \left[1 - (1 - \lambda)^{2i}\right]}{2 - \lambda}} \quad .$$
(15)

Here, L is the width of the control limits when the process is in the control state. The process is considered to be out of control whenever  $SC_i$  exceeds UCL<sup>1</sup> or  $(Y_i, Z_i)$  is outside the control region  $\{(Y_i, Z_i): Y_i + Z_i \leq \text{UCL}^2\}$ , and some action should be taken. Indeed, the latter method of determining when a process is out of control is preferable, because the source of an assignable cause can be directly identified by plotting the location of the sample point on the chart.

## 3. Cost model

Lorenzen and Vance's cost model (1986) is employed for determining the optimal decision values of the economic-statistical design of control charts. Some underlying assumptions in that cost model are: (1) The production cycle length is defined as the time interval from the start of the in-control state to the elimination of an assignable cause for the out-of-control state. (2) The time between the occurrences of an assignable cause follows an exponential distribution with a mean of  $1/\theta$  hours. (3) Once the process is out of control, intervention is required to adjust the process and return it to the initial state of statistical control. The expected cost per hour, denoted by E(A), is derived by dividing the expected cost per cycle by the expected cycle length. Thus,

$$\begin{split} E(A) &= \left\{ \frac{a+bn}{h} (\frac{1}{\theta} + h \cdot ARL_1 - \tau + nT_1 + \gamma_2 T_2 + \gamma_3 T_3) \right\} \div \left\{ \frac{1}{\theta} + h \cdot ARL_1 - \tau \\ &+ (1-\gamma_2) \frac{n_s \times T_0}{ARL_0} + nT_1 + T_2 + T_3 \right\} + \left\{ \frac{c_0}{\theta} + c_1 (h \cdot ARL_1 - \tau + nT_1 + \gamma_2 T_2 + \gamma_3 T_3) \\ &+ \frac{n_s \cdot c_2}{ARL_0} + c_3 \right\} \div \left\{ \frac{1}{\theta} + h \cdot ARL_1 - \tau + (1-\gamma_2) \frac{n_s \times T_0}{ARL_0} + nT_1 + T_2 + T_3 \right\} \end{split}$$

where,

n = sample size,

*h* = time interval between samples,

 $\lambda$  = smoothing constant of the control chart,

*L* = control limit constant of the control chart,

 $\tau = \text{expected time between an assignable cause and the prior sample, denoted by} [1 - (1 + \theta h)e^{-\theta \cdot h}] / \theta (1 - e^{-\theta \cdot h}),$ 

 $n_s$  = expected number of samples taken while in control, denoted  $e^{-\theta h} / (1 - e^{-\theta h})$ ,

 $\mu_0$  = target process mean,

 $\sigma_0$  = target process standard deviation,

 $T_0$  = expected time to search a false alarm,

 $T_1$  = expected time to sample, inspect and plot each sample unit,

 $T_2$  = expected time to search the assignable cause,

 $T_3$  = expected time to repair the assignable cause,

 $\gamma_2$  =1 if production continuous during searches,

=0 if production ceases during searches,

 $\gamma_3$  =1 if production continuous during repair,

=0 if production ceases during repair,

- *a* = fixed cost of sampling,
- *b* = unit variable cost of sampling,

 $C_0$  = the expected quality loss per unit of product when the process is in control,

 $C_1$  = the expected quality loss per unit of product when the process is out of control,

 $C_2$  = cost of investigating a false alarm,

 $c_3 = \text{cost of searching and repairing an assignable cause.}$ 

Traditionally, a product is classified as either conforming or nonconforming according to the specifications of the relevant quality characteristic. Quality costs are consequently incurred when products fall outside the specification limits. However, in practice, a product's performance will gradually deteriorate as the design parameter deviates from the target value. A loss function was first introduced by Taguchi (1985) to describe the quality characteristic differs from the nominal. The loss refers to the quality cost that is incurred when the quality characteristic is off target even though it may conform to the specification limits. Taguchi's loss function has been broadly employed in industrial applications, especially in the economic or economic-statistical designs of control charts (Serel and Moskowitz, 2008; Serel, 2009; Yeong et al., 2013; Lu et al., 2013). The economic-statistical designs of control charts based on Taguchi's loss function are investigated in this paper.

Since the symmetric loss function is more common in applications, in this paper, we consider symmetric loss functions and the constant loss coefficient K such that the quadratic function is presented as

$$L_{Q}(x) = K(x-T)^{2}, (16)$$

where the quality characteristic x has a probability density function f(x), the target value T is a parameter describing the risk aversion of the decision makers.

When the process is in control  $J_{0Q}$  is the expected loss per unit of product and we denote it as follows:

$$J_{0Q} = \int_{-\infty}^{\infty} L_Q(x) f(x) dx = K[\sigma_0^2 + (\mu_0 - T)^2]$$
<sup>(17)</sup>

When the process is out of control, the process mean shifts to  $\mu_1 = \mu_0 + \delta \sigma_0$  and/or the process variance shifts to  $\sigma_1 = \rho \sigma_0$ . The expected loss per unit of product is named  $J_{10}$  and represented as follows:

$$J_{1Q} = K[\sigma_1^2 + (\mu_0 - T)^2 + \delta^2 \sigma_0^2 - 2\delta \sigma_0(\mu_0 - T)]$$
(18)

Assume the production rate to be P units per hour. The quality costs  $c_0$  and  $c_1$  in Lorenzen and Vance's cost model are replaced with the two expected product losses  $J_{0Q}P$  and  $J_{10}P$ , respectively.

Consider the cost model integrating the loss function, wherein quality costs  $c_0$  and  $c_1$  are replaced by  $J_{0Q}P$  and  $J_{1Q}P$ , respectively. Consequently, the expected cost (or loss) per hour, denoted by  $E(\tilde{A})$ , may be expressed as

$$\begin{split} \min E(\tilde{A}) &= \left\{ \frac{a+bn}{h} (\frac{1}{\theta} + h \cdot ARL_1 - \tau + nT_1 + \gamma_2 T_2 + \gamma_3 T_3) \right\} \div \left\{ \frac{1}{\theta} + h \cdot ARL_1 - \tau \\ &+ (1-\gamma_2) \frac{n_s \times T_0}{ARL_0} + nT_1 + T_2 + T_3 \right\} + \left\{ \frac{J_{0Q}P}{\theta} + J_{1Q}P(h \cdot ARL_1 - \tau + nT_1 + \gamma_2 T_2 + \gamma_3 T_3) \\ &+ \frac{n_s \cdot c_2}{ARL_0} + c_3 \right\} \div \left\{ \frac{1}{\theta} + h \cdot ARL_1 - \tau + (1-\gamma_2) \frac{n_s \times T_0}{ARL_0} + nT_1 + T_2 + T_3 \right\} \\ &\text{subject to} \\ &ARL_0 \ge ARL_0^* \\ &n \in I^+, h, \ L \in \mathbb{R}^+, 0 < \lambda \le 1 \end{split}$$

Not only is the objective function  $E(\tilde{A})$  a function of  $ARL_0$  and  $ARL_1$ , but  $ARL_0$  and  $ARL_1$  are functions of the charting parameters of the control charts. Hence, the optimal decision variables  $(n^*, h^*, L^*, \lambda^*)$  of the economic-statistical design of the control charts based on loss functions are determined by minimizing the objective function  $E(\tilde{A})$ . Table 1 presents the

algorithmic description used to solve the objective functions of the economic-statistical designs of the control charts based on loss functions.

## 4. An example

The minimal expected cost and corresponding optimal decision variables are compared among the SS-EWMA, MaxEWMA, and EWMA-SC charts based on quadratic loss function. For this illustration, the following parameter values are employed to demonstrate the optimal economic-statistical design of the three charts: a=5, b=1,  $c_2=300$ ,  $c_3=150$ ,  $\theta=0.01$ ,  $K=1,T_0=2$ ,  $T_1=0.5$ ,  $T_2=2$ ,  $T_3=0$   $\delta \in \{0,0.5,1,2\}$ ,  $\rho \in \{1,1.5,2,3\}$ ,  $\gamma_2=1$ ,  $\gamma_3=0$ , r=1, and P=300. For the desired in-control process,  $ARL_0$  is set to 370. The optimal decision variables  $(n^*,h^*,L^*,\lambda^*)$  and optimal values of the economic-statistical design for various SS-EWMA, MaxEWMA, and EWMA-SC charts based on loss function are summarized in Tables 1-3.

function					
		$\rho = 1.00$	$\rho = 1.50$	$\rho = 2.00$	$\rho = 3.00$
	$n^*$	-	5	2	2
	$\lambda^{*}$	-	0.35	0.84	0.91
\$ 0.00	$h^{*}$	-	0.76	0.47	0.48
$\delta = 0.00$	$L^{*}$	-	4.765	4.908	4.910
	$ARL_1$	-	6.475	4.760	2.035
	$E(\widetilde{A})^{\min}$	-	346.60	360.84	404.11
	$n^*$	7	4	2	2
	$\lambda^{*}$	0.19	0.42	0.80	0.90
\$ 0.50	$h^{*}$	1.88	0.72	0.48	0.48
$\delta = 0.50$	$L^{*}$	4.476	4.814	4.909	4.991
	$ARL_{1}$	7.381	5.332	4.288	1.994
	$E(\widetilde{A})^{\min}$	319.69	346.25	362.44	406.36
	$n^*$	4	3	2	2
	$\lambda^{*}$	0.34	0.51	0.72	0.91
\$ 1.00	$h^{*}$	1.06	0.67	0.50	0.47
$\delta = 1.00$	$L^{*}$	4.750	4.854	4.902	4.910
	$ARL_1$	3.888	3.700	3.333	1.886
	$E(\widetilde{A})^{\min}$	331.76	350.56	367.74	413.12
	$n^*$	2	2	2	2
	$\lambda^{*}$	0.58	0.70	0.77	0.91
\$ 2.00	$h^{*}$	0.63	0.57	0.53	0.46
$\delta = 2.00$	$L^{*}$	4.880	4.901	4.908	4.910
	$ARL_1$	2.269	2.141	1.940	1.589
	$E(\widetilde{A})^{\min}$	361.21	374.73	392.29	440.14

Table 1. The optimal economic-statistical design of SS-EWMA charts under qu	uadratic loss

Table 2. The optimal economic-statistical design of MaxEWMA charts under quadratic loss function

		runction				
		$\rho = 1.00$	$\rho = 1.50$	$\rho = 2.00$	$\rho = 3.00$	
$\delta = 0.00$	$n^*$	_	5	3	2	
	$\lambda^{*}$	-	0.30	0.73	0.88	

3rd International Academic Conference in Paris (IACP), 10-11th August 2015, Paris, France

	The Business and Management Review, Volume 6 Number 4				
	$h^{*}$	-	0.74	0.58	0.46
	$L^{*}$	-	3.347	3.436	3.444
	$ARL_1$	-	6.834	3.709	2.140
	$E( ilde{A})^{\min}$	-	347.44	362.34	405.21
	$n^*$	7	4	2	2
	$\lambda^{*}$	0.19	0.39	0.71	0.90
\$ 0.50	$h^{*}$	1.92	0.69	0.46	0.46
$\delta = 0.50$	$L^{*}$	3.239	3.389	3.438	3.445
	$ARL_1$	7.098	5.878	4.617	2.092
	$E( ilde{A})^{\min}$	319.40	347.74	363.81	407.21
	$n^*$	4	3	2	2
	$\lambda^{*}$	0.35	0.48	0.73	0.90
\$ 1.00	$h^{*}$	1.08	0.65	0.48	0.46
$\delta = 1.00$	$L^{*}$	3.374	3.412	3.440	3.445
	$ARL_1$	3.726	3.943	3.540	1.971
	$E( ilde{A})^{\min}$	331.31	351.53	368.86	414.11
5 200	$n^*$	2	2	2	2
	$\lambda^{*}$	0.76	0.77	0.82	0.90
	$h^{*}$	0.65	0.57	0.51	0.45
$\delta = 2.00$	$L^{*}$	3.441	3.442	3.443	3.445
	$ARL_1$	2.166	2.158	2.012	1.645
	$E( ilde{A})^{\min}$	360.48	374.87	393.02	440.99

			function		
		$\rho = 1.00$	$\rho = 1.50$	$\rho = 2.00$	$\rho = 3.00$
C 0.00	$n^*$	-	3	2	2
	$\lambda^{*}$	-	0.15	0.23	0.41
	$h^{*}$	-	0.67	0.55	0.51
$\delta = 0.00$	$L^{*}$	-	3.110	3.617	4.194
	$ARL_1$	-	6.525	3.669	1.864
	$E( ilde{A})^{\min}$	-	340.74	356.32	402.24
	$n^*$	7	3	2	2
	$\lambda^{*}$	0.05	0.17	0.25	0.44
S 0.50	$h^{*}$	1.12	0.68	0.55	0.50
$\delta = 0.50$	$L^{*}$	2.288	3.204	3.696	4.270
	$ARL_1$	24.627	5.351	3.424	1.835
	$E( ilde{A})^{\min}$	330.80	342.93	358.52	404.56
δ=1.00	$n^*$	5	2	2	2
	$\lambda^{*}$	0.16	0.19	0.30	0.47
	$h^{*}$	0.94	0.56	0.55	0.50
	$L^{*}$	3.024	3.444	3.874	4.339
	$ARL_1$	5.732	4.659	2.870	1.753
	$E( ilde{A})^{\min}$	337.77	349.45	365.08	411.50
$\delta = 2.00$	n <sup>*</sup>	2	2	2	2

3<sup>rd</sup> International Academic Conference in Paris (IACP), 10-11<sup>th</sup> August 2015, Paris, France

243

The Busi	The Business and Management Review, Volume 6 Number 4				
 λ*	0.30	0.38	0.43	0.54	
$h^{*}$	0.62	0.58	0.54	0.48	
$L^{*}$	3.874	4.115	4.245	4.481	
$ARL_1$	2.361	2.080	1.849	1.521	
$E( ilde{A})^{\min}$	361.84	374.22	391.34	439.06	

## 5. Conclusion

A single EWMA control chart has good statistical performance in detecting both the mean and the variance shifts simultaneously. It only measures control chart from statistical performance viewpoint. Control charts based on pure economically are unable to satisfy requests in practice when they just pay attention to minimization quality costs but neglect the high false alarm rate. Therefore, this work investigates an economic-statistical design of SS-EWMA, MaxEWMA and EWMA-SC control charts for monitoring process mean and/or variance by incorporating the Taguchi's quadratic loss function into Lorenzen and Vance's cost model. Numerical simulations are conducted to evaluate effects of main input factors on the optimal economic-statistical design of these three control charts.

Numerical simulations reveal that the optimal sample size  $n^*$ , sampling interval  $h^*$  and out-of-control *ARL*<sub>1</sub> decrease as the magnitude of mean and/or variance shifts increases, obviously in small process shifts. However, the optimal control limit  $L^*$  and smoothing constant

 $\lambda^*$  increase as optimal value of  $E(\tilde{A})^{\min}$  increases. Moreover, it is reasonable that the optimal

value of  $E(\tilde{A})^{\min}$  increases as the mean shift  $\delta$  and/or variance shift  $\rho$  become large. Moreover, the MaxEWMA charts have the minimal cost when a process just has shifts in the mean. Once a process has shifts caused from the process variability, the EWMA-SC charts need minimal cost among these three charts.

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